

Robots in public spaces: towards multi-party, short-term, dynamic human-robot interaction

27 October 2013

09:00 – 09:40	Introduction	Manuel Giuliani, Ron Petrick
09:40 – 10:40	Invited Talk	Dan Bohus <i>Dialog in the Open-World: Challenges and Opportunities</i>
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10:40 – 11:10	<i>Coffee break (provided by conference)</i>	
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11:10 – 11:35	Paper	C. Granata, P. Bidaud, J. Bourgeois, C. Poirey, P. Robert <i>Pilot study of a socially assistive robot for the practice of the medical examination in hospital of adults with cognitive disabilities</i>
11:35 – 12:00	Paper	Yasir Tahir, Umer Rasheed, Keng Hui, Shoko Dauwels, Justin Dauwels, Daniel Thalmann, Nadia Magnenat-Thalmann <i>NAO Robot as a Social Mediator: A User Study</i>
12:00 – 12:25	Paper	Simon Keizer, Pantelis Kastoris, Mary Ellen Foster, Amol Deshmukh, Oliver Lemon <i>User evaluation of a multi-user social interaction model implemented on a Nao robot</i>
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12:30 – 13:30	<i>Lunch (provided by conference)</i>	
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13:30 – 14:30	Invited talk	Jon Barker <i>Towards Human-Robot Spoken Communication in Everyday Environments</i>
14:30 – 14:55	Paper	A. Meddahi, R. Chellali <i>The Particle Swarm Optimization: A Flexible approach to Generate Robot Behaviors</i>
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14:55 – 15:30	<i>Coffee break (provided by conference)</i>	
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15:30 – 15:45	Abstract	Michiel Joose, Manja Lohse, Vanessa Evers <i>Short Duration Robot Interaction at an Airport: Challenges from a Socio-Psychological Point of View</i>
15:45 – 16:00	Abstract	Karola Pitsch, Raphaela Gehle, Sebastian Wrede <i>A museum guide robot: Dealing with multiple participants in the real-world</i>
16:00 – 16:30	Closing notes, open discussion	